

SELECTION AND APPLICATION OF ELECTRICAL MOTORS

- HIGH STARTING TORQUE
- FREQUENT STARTING
- FREQUENT REVERSING
- DUTY CYCLE LOADING
- HIGH LOAD INERTIA
- FREQUENT PEAK TORQUE
- VARIABLE SPEED

CHARACTERISTICS OF MOTOR

CHARACTERISTICS OF LOAD

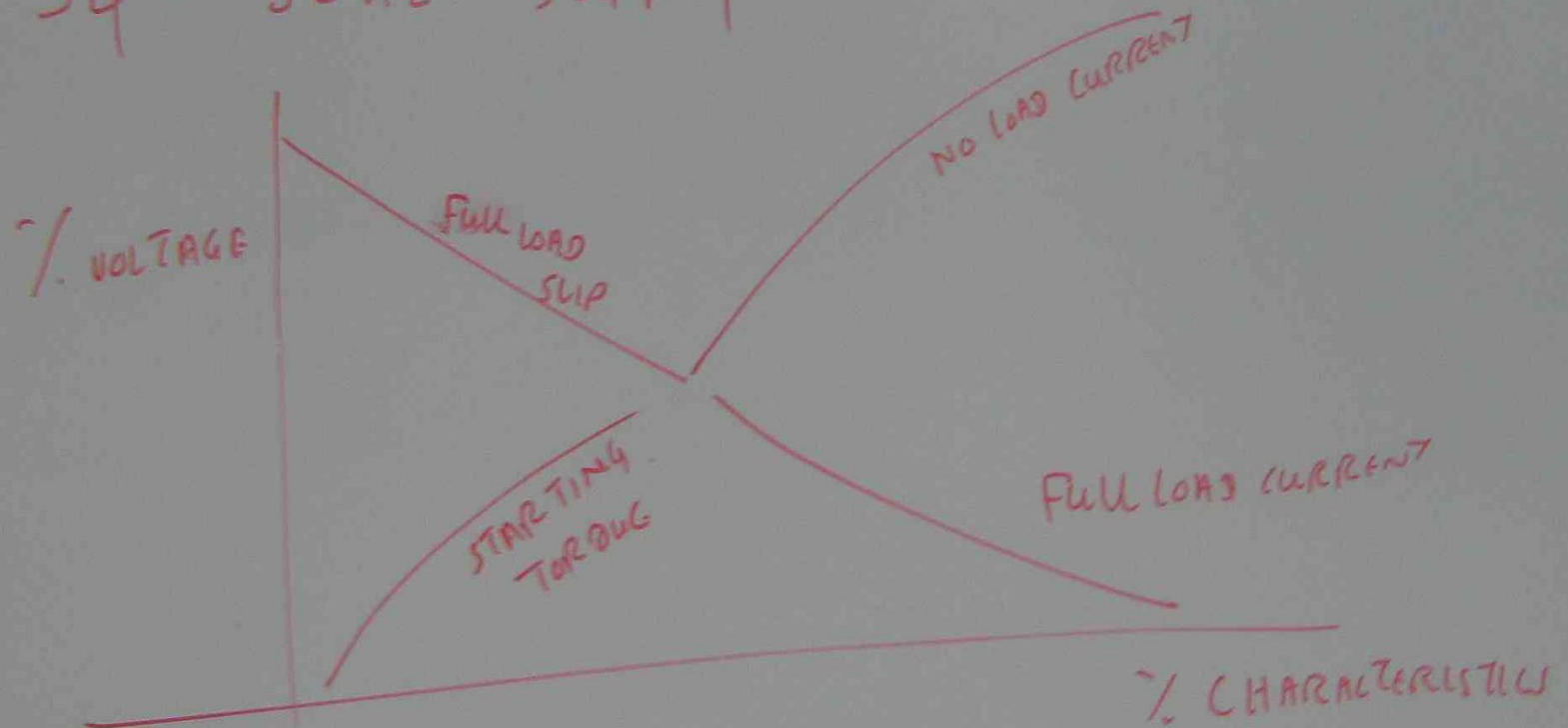
MATCHING THE MOTOR TO LOAD

VOLTAGE, FREQUENCY, TYPE OF SUPPLY

RATED VOLTAGE	MAXIMUM RATED OUTPUT
415V	-
3.3kV	150kW
6.6kV	300kW
11kV	750kW

FREQUENCY VARIATION = $\pm 5\%$ OF NAME PLATE RATING

3 ϕ 50Hz supply



EFFECT OF UNBALANCED VOLTAGE ON MOTOR PERFORMANCE

MAXIMUM DEVIATION FROM AVERAGE VOLTAGE

% VOLTAGE IMBALANCE =

AVERAGE VOLTAGE

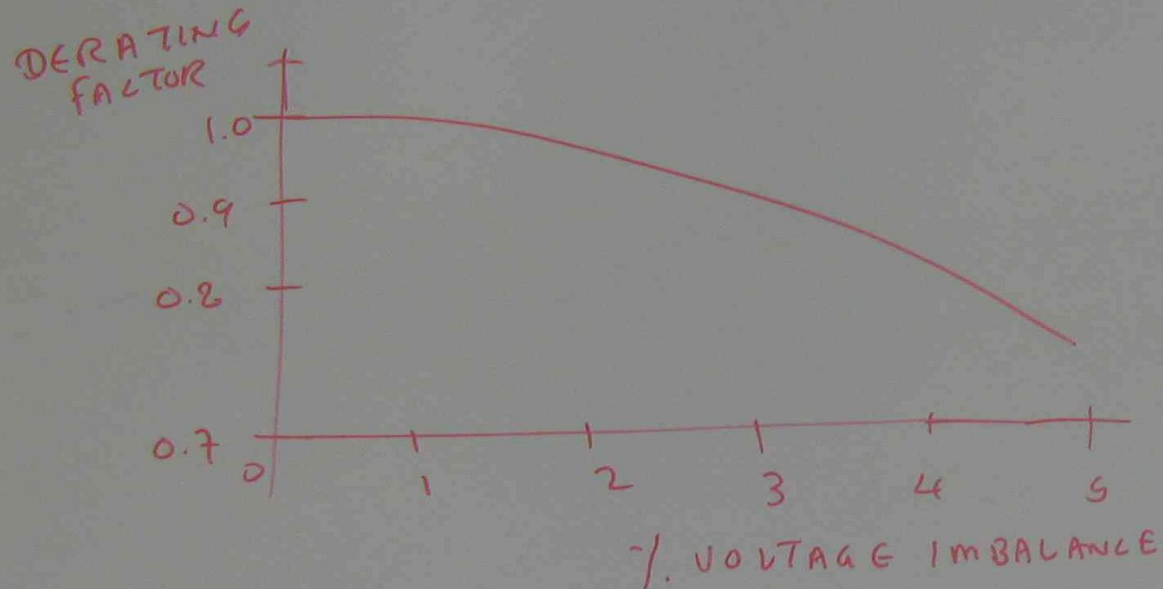
$\times 100$

Pb THREE VOLTAGES, PHASE TO NEUTRAL ARE MEASURED
TO BE 220, 215 AND 210 V ON NOMINAL 415V, 50Hz
SUPPLY. DETERMINE THE % VOLTAGE IMBALANCE FOR 220V.

$$\text{AVERAGE VOLTAGE} = \frac{220 + 215 + 210}{3} = 215\text{V}$$

$$\% \text{ VOLTAGE IMBALANCE} = \frac{220 - 215}{215} \times 100 = 2.3\%$$

RELATIONSHIP BETWEEN % VOLTAGE IMBALANCE AND DERATING FACTOR



POWER OUT PUT

COMMONLY AVAILABLE OUT PUT RATINGS OF MOTOR (KW)

0.37, 0.55, 0.75,

1.1, 1.5, 2.2, 3.0, 4.0, 5.5, 7.5

11, 15, 18.5, 22, 30, 37, 45, 55, 75, 90

110, 132, 150, 185, 220, 250

SPEED

$$N_s = \frac{60 f}{\text{No. of poles}}$$

(SYNCHRONOUS SPEED)

SLIP

$$\text{SLIP SPEED} = \frac{N_s - N_r}{N_s}$$

SQUIRREL CAGE INDUCTION MOTOR

$$\text{SLIP} = 4\%$$

MOTOR CURRENT



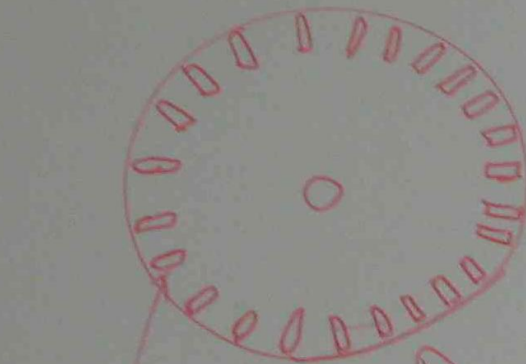
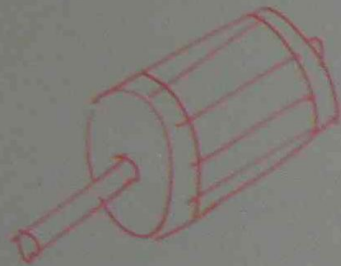
VOLTAGE

MOTOR TORQUE

$$\propto (\text{VOLTAGE})^2$$

CONSTRUCTION OF MOTOR ROTOR

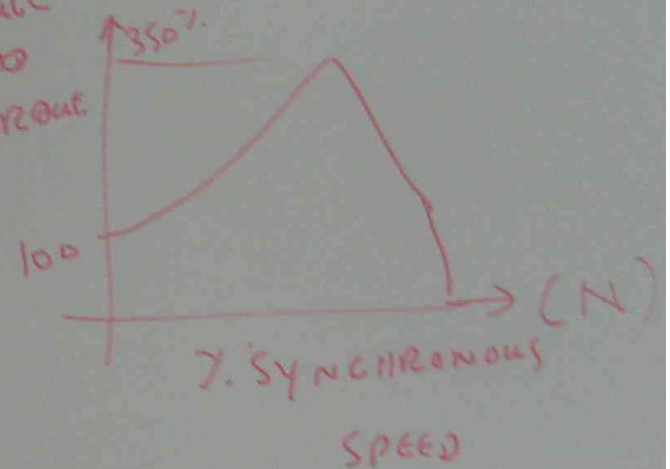
NORMAL CAGE



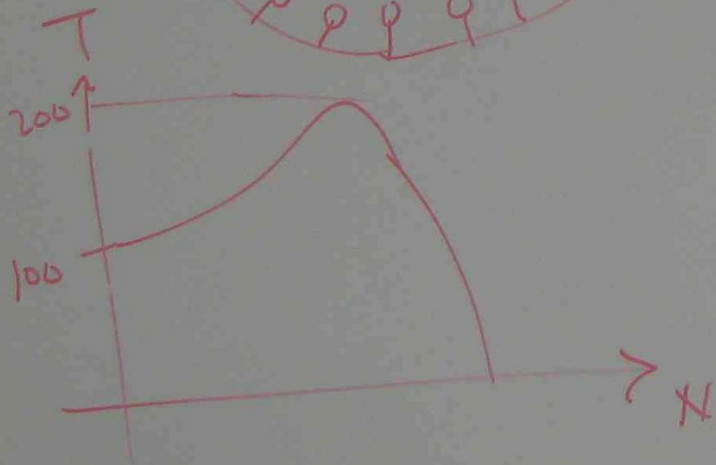
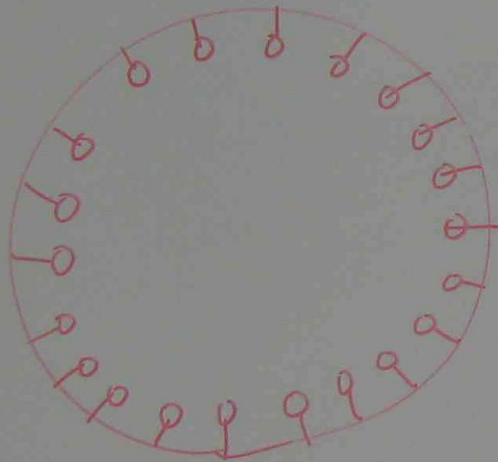
CONDUCTOR
BARS

ROTOR

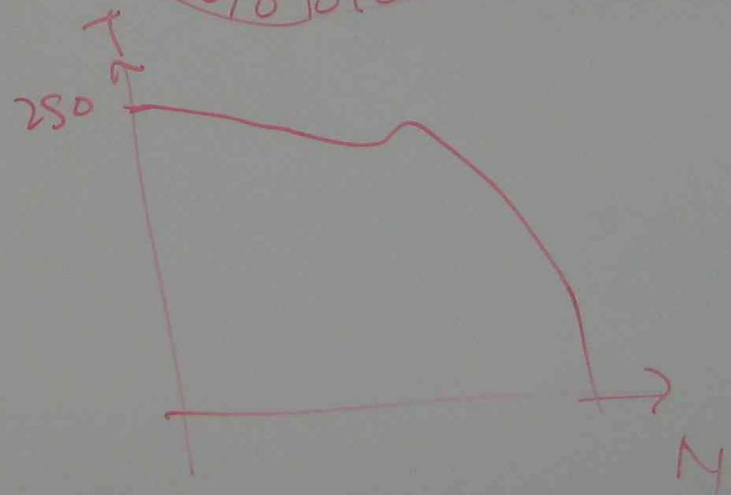
(T) % Full
LOAD
TORQUE



SASH BAR



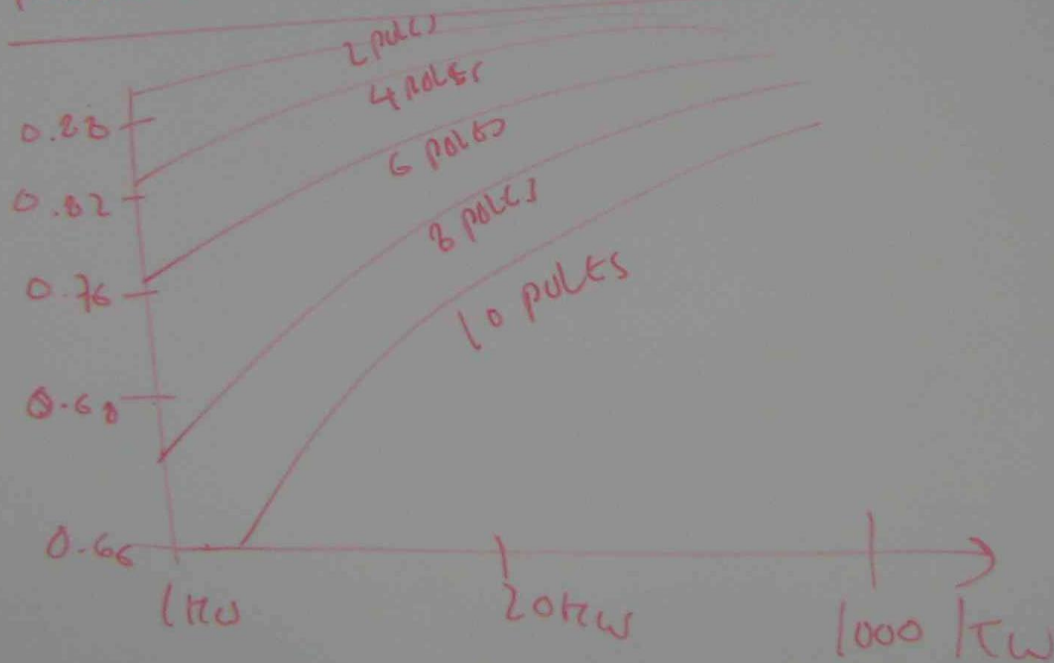
DOUBLE CAGE



STARTING CURRENT OF 3 ϕ INDUCTION MOTOR

450% \longrightarrow 600%

POWER FACTOR & EFFICIENCY



10 poles

$$N = \frac{120 f}{P}$$

$$= \frac{120 \times 50}{10}$$

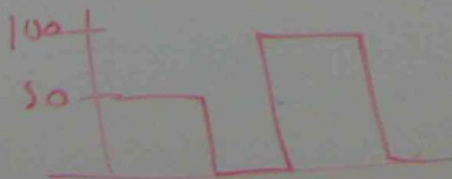
$$= 600 \text{ rpm}$$

DUTY CYCLE AND CLASSES OF RATING

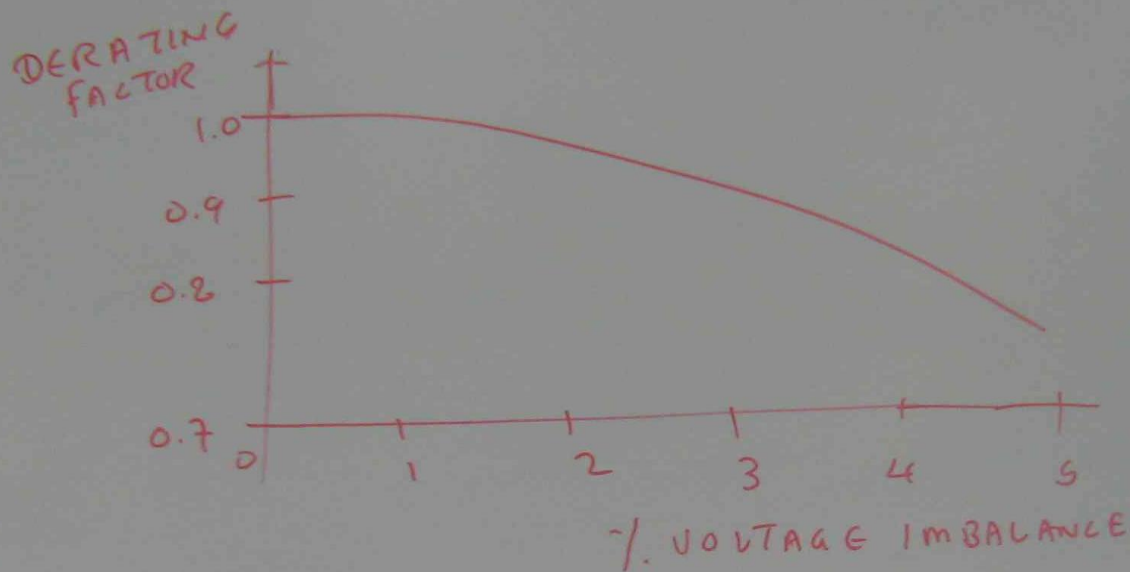
IN THE DETERMINATION OF THE TYPE AND DESIGN OF MOTOR, THE FOLLOWING TWO IMPORTANT FACTORS MUST BE CONSIDERED.

- THE DRIVING TORQUE MUST BE CAPABLE OF SUPPLYING THE MAXIMUM TORQUE LIKELY TO BE ENCOUNTERED AT ANY TIME
- TO AVOID DAMAGE TO THE INSULATION OF THE WINDINGS, THE RESULTING TEMPERATURE RISE MUST NOT EXCEED TO RATED VALUE.

70%, 80% OF CONTINUOUS RATINGS



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(SYNCHRONOUS SPEED)

SLIP

$$\text{SLIP SPEED} = \frac{N_s - N_r}{N_s}$$

SCREWDRIVER CAGE INDUCTION MOTOR

$$\text{SLIP} = 4 \%$$

MOTOR CURRENT \propto VOLTAGE

MOTOR TORQUE $\propto (\text{VOLTAGE})^2$

