

Power System Analysis

- **Fundamentals of Power Systems (EEL 3216)**

- ◆ basic models of power apparatus,
 - transformers, synchronous machines, transmission lines
- ◆ simple systems
 - one feeder radial to single load

- **What more is there?**

- ◆ large interconnected systems
 - multiple loads; multiple generators
- ◆ why have large interconnected systems?
 - reliability; economics
- ◆ analysis of the large system
 - flow of power and currents; control and stability of the system
 - proper handling of fault conditions; economic operation

Modern Power Systems

- **Power Producer**
 - ◆ generation station
 - prime mover & generator
 - step-up transformer
- **Transmission Company**
 - ◆ HV transmission lines
 - ◆ switching stations
 - circuit breakers
 - transformers
- **Distribution Utility**
 - ◆ distribution substations
 - step-down transformers
 - ◆ MV distribution feeders
 - distribution transformers



Network Layout

- **HV Networks**

- ◆ Large quantities of power shipped over great distances
- ◆ Sharing of resources
 - Improved reliability
 - Economics of large scale

- **MV Networks**

- ◆ Local distribution of power
- ◆ Numerous systems
 - Economics of simplicity
 - Autonomous operation

- **Loads**

- ◆ Industrial & Commercial
- ◆ Residential



System Control

- **Network Protection**

- ◆ Switchgear

- instrumentation transformers
 - circuit breakers
 - disconnect switches
 - fuses
 - lightning arrestors
 - protective relays

- **Energy Management Systems**

- ◆ Energy Control Center

- computer control
 - SCADA - Supervisory Control And Data Acquisition



Computer Analysis

- **Practical power systems**
 - ◆ must be safe
 - ◆ reliable
 - ◆ economical
- **System Analysis**
 - ◆ for system planning
 - ◆ for system operations
 - ◆ requires component modeling
 - ◆ types of analysis
 - transmission line performance
 - power flow analysis
 - economic generation scheduling
 - fault and stability studies



Chapter 2

AC Power

Single-Phase Power Consumption

$$v(t) = V_m \cos(\omega t + \theta_v)$$

$$i(t) = I_m \cos(\omega t + \theta_i)$$

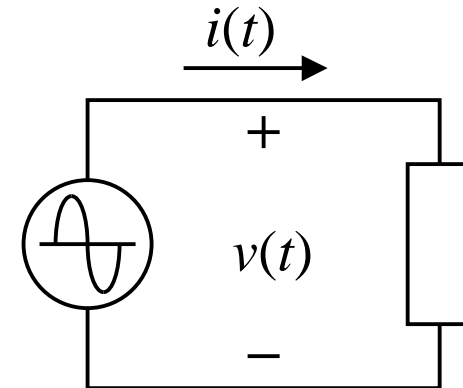
$$p(t) = v(t) i(t) = V_m I_m \cos(\omega t + \theta_v) \cos(\omega t + \theta_i)$$

$$\cos A \cos B = \frac{1}{2} \cos(A - B) + \frac{1}{2} \cos(A + B)$$

$$p(t) = \frac{1}{2} V_m I_m \{ \cos(\theta_v - \theta_i) + \cos(2\omega t + \theta_v + \theta_i) \}$$

$$\theta = \theta_v - \theta_i \quad V_m = \sqrt{2} |V| \quad I_m = \sqrt{2} |I|$$

$$p(t) = \underbrace{|V| |I| \cos \theta \{1 + \cos 2(\omega t + \theta_v)\}}_{\text{energy flow into the circuit}} + \underbrace{|V| |I| \sin \theta \sin 2(\omega t + \theta_v)}_{\text{energy borrowed and returned by the circuit}}$$



Average Active (Real) Power

$$p(t) = |V| |I| \{1 + \cos 2(\omega t + \theta_v)\} \cos \theta + |V| |I| \sin 2(\omega t + \theta_v) \sin \theta$$

$$\bar{P} = \frac{1}{2\pi} \int_0^{2\pi} p(t) dt$$

$$= |V| |I| \int_0^{2\pi} \{1 + \cos 2(\omega t + \theta_v)\} \cos \theta + \sin 2(\omega t + \theta_v) \sin \theta dt$$

$$\int_0^{2\pi} \cos(\omega t) dt = 0 \quad \int_0^{2\pi} \sin(\omega t) dt = 0$$

$$\bar{P} = |V| |I| \cos \theta$$

$$pf = \cos \theta = \frac{\bar{P}}{|V| |I|}$$

Apparent Power

$$\bar{P} = |V| |I| \cos \theta$$

$$S = |V| |I|$$

$$p(t) = |V| |I| \{1 + \cos 2(\omega t + \theta_v)\} \cos \theta + |V| |I| \sin 2(\omega t + \theta_v) \sin \theta$$

$$p_R(t) = |V| |I| \{1 + \cos 2(\omega t + \theta_v)\} \cos \theta = \bar{P} \{1 + \cos 2(\omega t + \theta_v)\}$$

$$p_X(t) = |V| |I| \sin 2(\omega t + \theta_v) \sin \theta = S \sin \theta \sin 2(\omega t + \theta_v)$$

Reactive Power

$$p_X(t) = |V| |I| \sin \theta \sin 2(\omega t + \theta_v) = S \sin \theta \sin 2(\omega t + \theta_v)$$

$$Q \equiv S \sin \theta = |V| |I| \sin \theta$$

$$p_X(t) = Q \sin 2(\omega t + \theta_v)$$

- **for a pure resistor**

- ◆ the impedance angle is zero, power factor is unity
- ◆ apparent power and real power are equal

- **for a purely inductive circuit**

- ◆ the current lags the voltage by 90°, average power is zero
- ◆ no transformation of energy

- **for a purely capacitive circuit**

- ◆ the current leads the voltage by 90°, average power is zero

AC Power

- **Example**

- ◆ the supply voltage is given by $v(t) = 480 \cos \omega t$
- ◆ the load is inductive with impedance $Z = 1.20 \angle 60^\circ \Omega$
- ◆ determine the expression for the instantaneous current $i(t)$ and instantaneous power $p(t)$
- ◆ plot $v(t)$, $i(t)$, $p(t)$, $p_R(t)$, $p_X(t)$ over an interval of 0 to 2π

Complex Power

- **Real Power, P**

- ◆ RMS based - thermally equivalent to DC power

- **Reactive Power, Q**

- ◆ Oscillating power into and out of the load because of its reactive element (L or C).
- ◆ Positive value for inductive load (lagging pf)

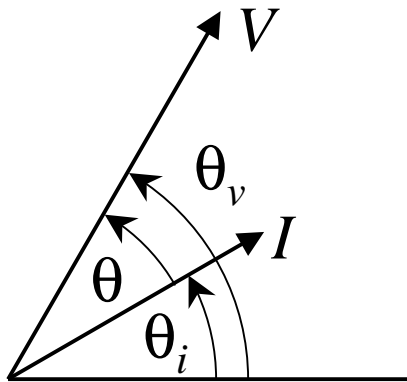
- **Complex Power, S**

$$V I^* = |V| |I| \angle (\theta_v - \theta_i) = |V| |I| \angle \theta = S$$

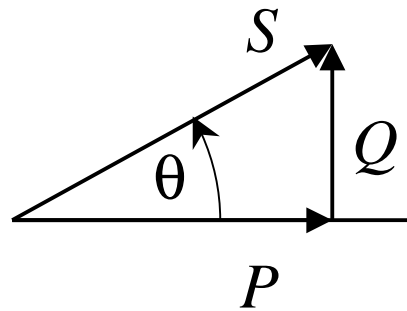
$$S = |V| |I| \cos \theta + j |V| |I| \sin \theta = P + jQ$$

$$|S| = \sqrt{P^2 + Q^2}$$

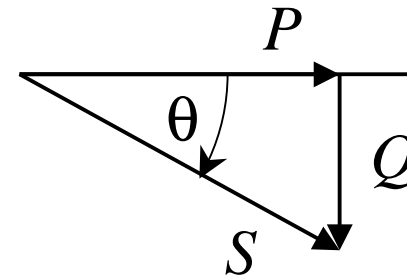
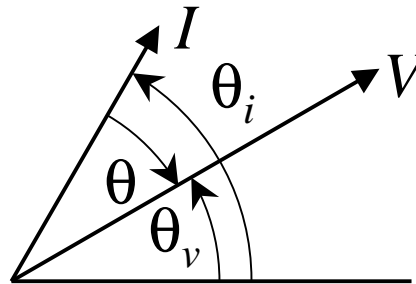
Complex Power



Lagging Power Factor



Leading Power Factor



The Complex Power Balance

- **From the conservation of energy**

- ◆ Real power supplied by the source is equal to the sum of the real powers absorbed by the load and the real losses in the system
- ◆ Reactive power must also be balanced
 - The balance is between the sum of leading and the sum of lagging reactive power producing elements
- ◆ The total complex power delivered to the loads in parallel is the sum of the complex powers delivered to each

$$0 = \sum P_{gen} - \sum P_{loads} - \sum P_{losses}$$

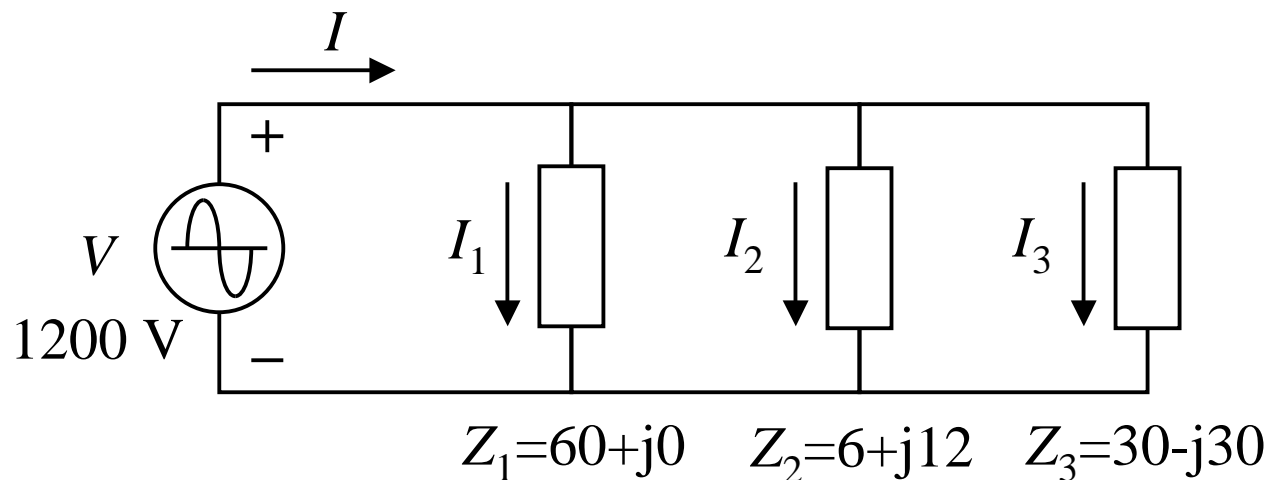
$$0 = \sum Q_{leading} + \sum Q_{caps} - \sum Q_{lagging} - \sum Q_{ind}$$

$$0 = \sum S_{gen} - \sum S_{loads} - \sum S_{losses}$$

Complex Power

- **Example**

- ◆ in the circuit below, find the power absorbed by each load and the total complex power
- ◆ find the capacitance of the capacitor to be connected across the loads to improve the overall power factor to 0.9 lagging



Complex Power Flow

- Consider the following circuit

- For the assumed direction of current

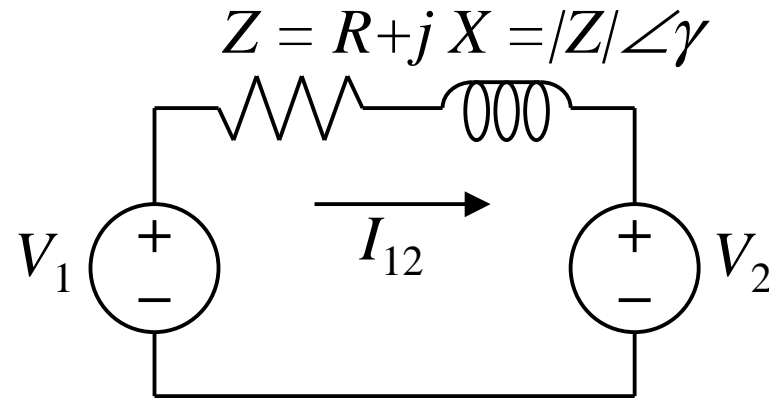
$$V_1 = |V_1| \angle \delta_1 \quad V_2 = |V_2| \angle \delta_2$$

$$I_{12} = \frac{|V_1| \angle \delta_1 - |V_2| \angle \delta_2}{|Z| \angle \gamma} = \frac{|V_1|}{|Z|} \angle (\delta_1 - \gamma) - \frac{|V_2|}{|Z|} \angle (\delta_2 - \gamma)$$

- The complex power

$$S_{12} = V_1 I_{12}^* = |V_1| \angle \delta_1 \left[\frac{|V_1|}{|Z|} \angle (\gamma - \delta_1) - \frac{|V_2|}{|Z|} \angle (\gamma - \delta_2) \right]$$

$$= \frac{|V_1|^2}{|Z|} \angle \gamma - \frac{|V_1| |V_2|}{|Z|} \angle (\gamma + \delta_1 - \delta_2)$$



Complex Power Flow

- ◆ The real and reactive power at the sending end

$$P_{12} = \frac{|V_1|^2}{|Z|} \cos \gamma - \frac{|V_1||V_2|}{|Z|} \cos(\gamma + \delta_1 - \delta_2)$$

$$Q_{12} = \frac{|V_1|^2}{|Z|} \sin \gamma - \frac{|V_1||V_2|}{|Z|} \sin(\gamma + \delta_1 - \delta_2)$$

- ◆ Transmission lines have small resistance compared to the reactance. Often, it is assumed $R = 0$ ($Z = X \angle 90^\circ$)

$$P_{12} = \frac{|V_1||V_2|}{X} \sin(\delta_1 - \delta_2) \quad Q_{12} = \frac{|V_1|}{|X|} [|V_1| - |V_2| \cos(\delta_1 - \delta_2)]$$

Complex Power Flow

- **For a typical power system with small R / X ratio, the follow observations are made**
 - ◆ Small changes in δ_1 or δ_2 will have significant effect on the real power flow
 - ◆ Small changes in voltage magnitude will not have appreciable effect on the real power flow
 - ◆ Assuming no resistance, the theoretical maximum power (static transmission capacity) occurs when the angular difference, δ , is 90° and is given by:
$$P_{\max} = \frac{|V_1||V_2|}{X}$$
 - ◆ For maintaining stability, the power system operates with small load angle δ
 - ◆ The reactive power flow is determined by the magnitude difference of the terminal voltages

Three-Phase Power

- **Balanced three-phase power**

- ◆ Assumes balanced loads
- ◆ Assumes voltage and currents with phases that have 120° separation

$$P_{3\phi} = 3 |V_p| |I_p| \cos \theta = \sqrt{3} |V_{LL}| |I_L| \cos \theta$$

$$Q_{3\phi} = 3 |V_p| |I_p| \sin \theta = \sqrt{3} |V_{LL}| |I_L| \sin \theta$$

$$S_{3\phi} = 3 V_p I_p^* = \sqrt{3} V_{LL} I_L^*$$

Chapter 3

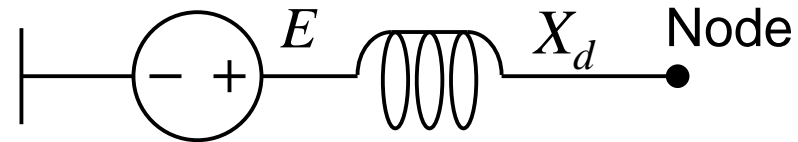
Power Apparatus Modeling

System Modeling

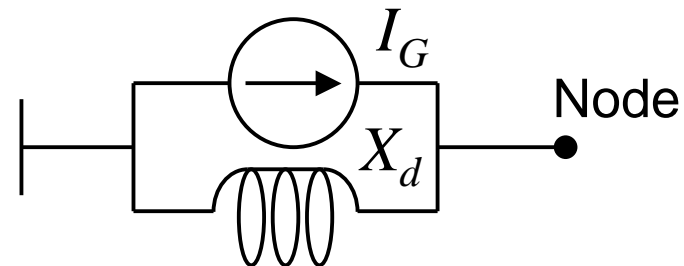
- **Systems are represented on a per-phase basis**
 - ◆ A single-phase representation is used for a balanced system
 - the system is modeled as one phase of a wye-connected network
 - ◆ Symmetrical components are used for unbalanced systems
 - unbalance systems may be caused by: generation, network components, loads, or unusual operating conditions such as faults
 - ◆ The per-unit system of measurements is used
- **Review of basic network component models**
 - ◆ generators
 - ◆ transformers
 - ◆ loads
 - ◆ transmission lines

Generator Models

- **Generator may be modeled in three different ways**
 - ◆ Power Injection Model - the real, P , and reactive, Q , power of the generator is specified at the node that the generator is connected
 - either the voltage or injected current is specified at the connected node, allowing the other quantity to be determined
 - ◆ Thevenin Model - induced AC voltage, E , behind the synchronous reactance, X_d

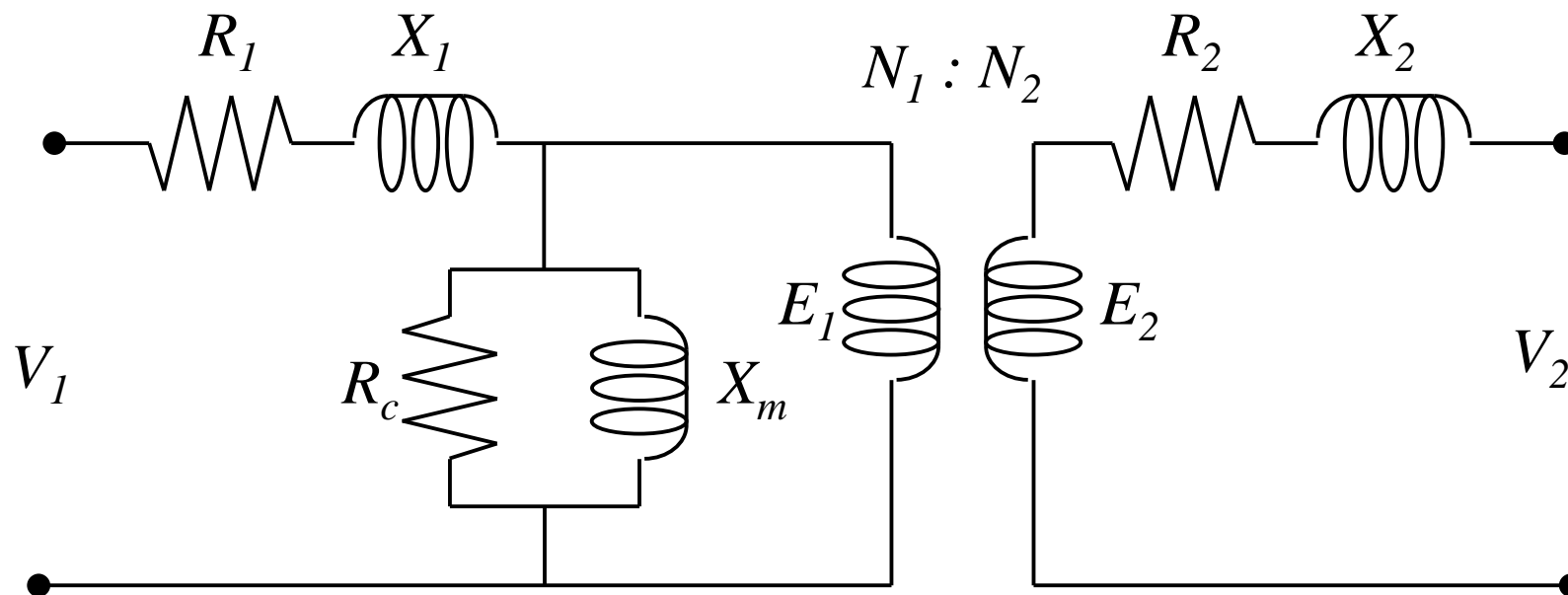


- ◆ Norton Model - injected AC current, I_G , in parallel with the synchronous reactance



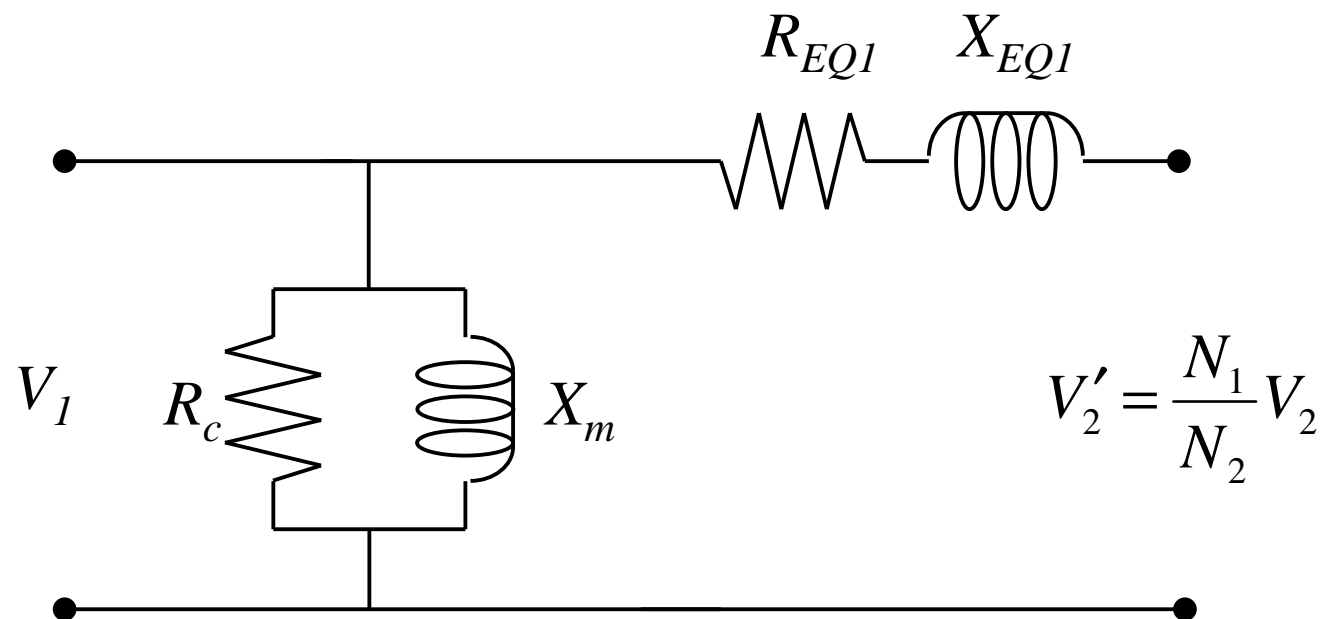
Transformer Model

- Equivalent circuit of a two winding transformer



Transformer Model

- Approximate circuit referred to the primary



Load Models

- **Models are selected based on both the type of analysis and the load characteristics**
- **Constant impedance, Z_{load}**
 - ◆ Load is made up of R , L , and C elements connected to a network node and the ground (or neutral point of the system)
- **Constant current, I_{load}**
 - ◆ The load has a constant current magnitude I , and a constant power factor, independent of the nodal voltage
 - ◆ Also considered as a current injection into the network
- **Constant power, S_{load}**
 - ◆ The load has a constant real, P , and reactive, Q , power component independent of nodal voltage or current injection
 - ◆ Also considered as a negative power injection into the network

Per Unit System

- Almost all power system analyses are performed in per-units

$$x_{per\ unit}(pu) = \frac{x_{engineering(actual)}(engr.\ unit)}{x_{base}(engr.\ unit)} = \frac{x\%}{100}$$

- Per unit system for power systems

- ◆ Based on a per-phase, wye-connect, three-phase system

- ◆ 3-phase power base, $S_{3\phi}$

- common power base is 100 MVA

- ◆ Line-to-line voltage base, V_{LL}

- voltage base is usually selected from the equipment rated voltage

$$I_{L-base} = \frac{S_{3\phi-base}}{\sqrt{3} V_{LL-base}}$$

- ◆ Phase current base, I_L

- ◆ Phase impedance base, Z

$$Z_{base} = \frac{(V_{LL-base})^2}{S_{3\phi-base}} = \frac{(V_{LN-base})^2}{S_{1\phi-base}}$$

Per Unit System

- **Equipment impedances are frequently given in per units or percentages of the impedance base**

- ◆ The impedance base for equipment is derived from the rated power and the rated voltage
- ◆ When modeling equipment in a system, the per unit impedance must be converted so that the equipment and the system are on a common base

$$Z_{pu}^{old} = \frac{Z_{\Omega}}{Z_{base}^{old}} = Z_{\Omega} \frac{S_{base}^{old}}{(V_{base}^{old})^2} \quad Z_{pu}^{new} = \frac{Z_{\Omega}}{Z_{base}^{new}} = Z_{\Omega} \frac{S_{base}^{new}}{(V_{base}^{new})^2}$$

$$Z_{pu}^{new} = \frac{S_{base}^{new}}{(V_{base}^{new})^2} \cdot \frac{(V_{base}^{old})^2}{S_{base}^{old}} \cdot Z_{pu}^{old} = Z_{pu}^{old} \frac{S_{base}^{new}}{S_{base}^{old}} \cdot \left(\frac{V_{base}^{old}}{V_{base}^{new}} \right)^2$$

- ◆ It is normal for the voltage bases to be the same: $Z_{pu}^{new} = Z_{pu}^{old} \frac{S_{base}^{new}}{S_{base}^{old}}$

Per Unit System

- **The advantages of the per unit system for analysis**
 - ◆ Gives a clear idea of relative magnitudes of various quantities
 - ◆ The per-unit impedance of equipment of the same general type based upon their own ratings fall in a narrow range regardless of the rating of equipment.
 - Whereas their impedances in ohms vary greatly with the ratings.
 - ◆ The per-unit impedance, voltages, and currents of transformers are the same regardless of whether they are referred to the primary or the secondary side.
 - Different voltage levels disappear across the entire system.
 - The system reduces to a system of simple impedances
 - ◆ The circuit laws are valid in per-unit systems, and the power and voltages equations are simplified since the factors of $\sqrt{3}$ and 3 are eliminated in the per-unit system

Per Unit System

- **Example**

- ◆ the one-line diagram of a three-phase power system is shown
- ◆ use a common base of 100 MVA and 22 kV at the generator
 - draw an impedance diagram with all impedances marked in per-unit
 - the manufacturer's data for each apparatus is given as follows

□ G:	90 MVA	22 kV	18%
□ T1:	50 MVA	22/220 kV	10%
□ L1:	48.4 ohms		
□ T2:	40 MVA	220/11 kV	6%
□ T3:	40 MVA	22/110 kV	6.4%
□ L2:	65.43 ohms		
□ T4:	40 MVA	110/11 kV	8%
□ M:	66.5 MVA	10.45 kV	18.5%
□ Ld:	57 MVA	10.45 kV	0.6 pf lag

